CALIBRATION STRIP

Sheet 1 of 3: START

Put the middle of the wheels on the black line and the middle of the robot on the dashed line.

The robot drives up the page.



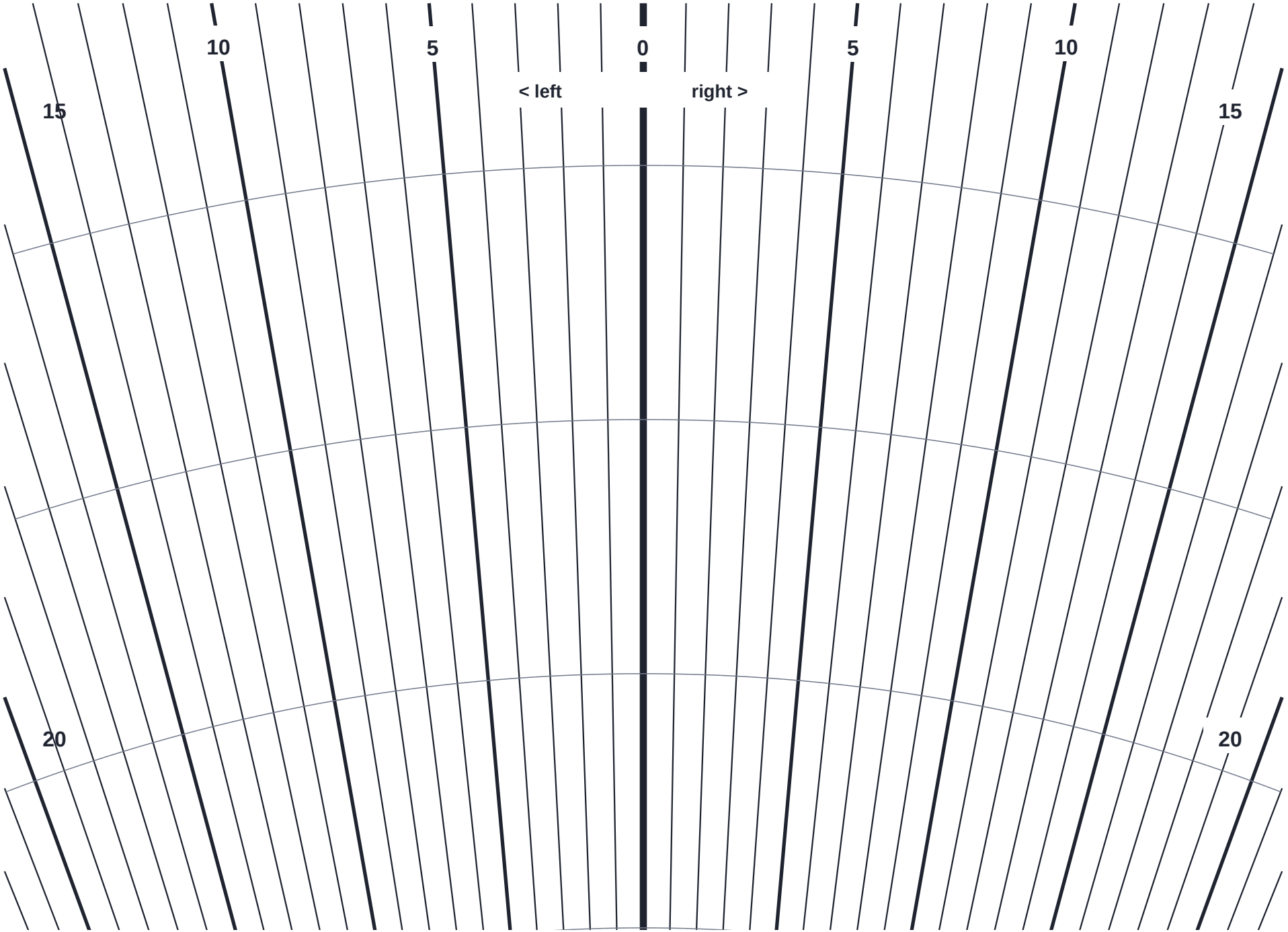
Tape the tape measure down along this edge, with its 0 at the start line.

tape measure 0 here >





10 cm: check this bar with a ruler (print at 100% / Actual size)



CALIBRATION STRIP Sheet 2 of 3: ANGLES

Put this edge at 28 cm on the tape measure, the right edge against it. Read the line under the middle of the robot's front.

CALIBRATION STRIP Sheet 3 of 3: DISTANCE (cm from the start line)



Put this edge at 68 cm on the tape measure, the right edge against it. Read the line beside the middle of the wheels (the hubs).